

Amendments to the Claims:

This listing of claims will replace all prior versions, and listings, of claims in the application:

Listing of Claims:

1. – 8. (Canceled):

9. (Currently Amended): A component placement device comprising:

a movable frame;

at least two component pick and place units that are connected to the movable frame;

and

at least two component feeding devices,

wherein the component placement device is configured to simultaneously pick-up components, by means of the component pick and place units, supplied by the component feeding devices, [[and]]

wherein at least one component pick and place unit is configured to be moved relative to the frame such that the respective positions of the component pick and place units are adjusted, and

wherein the at least one component pick and place unit is independently moveable relative to the frame in a direction equal to and opposite to a X-direction and in a direction equal to and opposite to a Y-direction.

10. (Previously Presented): The component placement device according to claim 9, wherein each component pick and place unit is configured to be moved relative to the frame.

11. (Currently Amended): The component placement device according to claim 9,

wherein a first of the component pick and place units is configured to be moved, in a first direction, relative to a second of the component pick and place units while the components that are to be supplied by means of the component feeding devices are moved relative to one another in a second direction, and

wherein the second direction is transverse to the first direction.

12. (Currently Amended): A method for picking-up components by ~~means of~~ a component placement device that is provided with a movable frame; at least two component pick and place units that are connected to the movable frame; and at least two component feeding devices, the method comprising the steps of:

setting components and the pick and place units relative to one another; and
picking-up the components simultaneously using each of the component pick and place units,

wherein at least one component pick and place unit is independently moveable relative to the frame in a direction equal to and opposite to a X-direction and in a direction equal to and opposite to a Y-direction.

13. (Previously Presented): The method according to claim 12, further comprising the step of:

adjusting the positions of the component pick and place units by moving at least one component pick and place unit relative to the frame.

14. (Previously Presented): The method according to claim 12, further comprising the steps of:

detecting, using a camera, the positions of the components to be picked-up from the component feeding devices; and

adjusting the positions of the component pick and place units on the basis of the positions of the components to be picked-up.

15. (Previously Presented): The method according to claim 12, further comprising the steps of:

determining actual positions of the components picked-up by the component pick and place units relative to the component pick and place units;

determining deviations, if any, between desired positions of the components and the actual positions of the components; and

moving, based on the deviations, the component pick and place units relative to one another prior to the step of picking-up the components.

16. (Previously Presented): The method according to claim 12, further comprising the steps of:

moving the pick and place units relative to one another in a first direction; and simultaneously moving, by means of the component feeding devices, the components to be picked-up relative to one another in a second direction that extends transverse to the first direction.

17. (New): A method for picking-up components by a component placement device that is provided with a movable frame; at least two component pick and place units that are connected to the movable frame; and at least two component feeding devices, the method comprising the steps of:

setting components and the pick and place units relative to one another;

picking-up the components simultaneously using each of the component pick and place units;

placing the components simultaneously on at least one substrate using each of the component pick and place units; and

moving the component pick and place units relative to one another prior to the step of placing the components simultaneously on at least one substrate and after picking-up the components, and

wherein at least one component pick and place unit is independently moveable relative to the frame in a direction equal to and opposite to a X-direction and in a direction equal to and opposite to a Y-direction.

18. (New): The method according to claim 17, wherein the components are placed on a single substrate.

19. (New): The method according to claim 17, wherein the components are placed on two substrates adjacent each other.